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excellence and passion in automatic control design



Automatic Control Design of the Amazing Ball with the EICASLAB suite



Webinar n.2 Modelling and Like Real-time Simulation



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Modelling and Like Real-time Simulation

- Operative mode overview
- Outstanding characteristics
 - Pre-organized Working Areas
 - Focus on HW/SW architecture
 - The two model approach
 - Powerful algorithms and oriented libraries
 - Like Real-time simulation
 - Automatic code generation of the Application Software



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Modelling and Like Real-time simulation

A practical use case: the EVIDENCE Amazing Ball



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Operative mode overview

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The **Modelling and Like Real-time simulation** is the EICASLAB operative mode specifically studied for supporting the user in:

- > designing the overall control strategy, and,
- preliminary assessing its performance in a powerful simulated environment, able to faithfully emulate "like real-time" the expected final software and hardware architecture.



For running this operative mode a standard PC equipped with Linux or Windows O/S and with the EICASLAB suite is required.

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Outstanding characterists: Support to system design Pre-organized Working Areas

Three pre-organised Working Areas are available:

• the Plant Area,

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- the Control Area,
- the Mission Area,

specifically devoted and customized to program the different parts of the project.





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Outstanding characterists: Support to system design Focus on HW/SW architecture

Since the beginning, special focus is given on hardware and software architecture.

Multi-processors and multi-level hierarchical controls can be easily designed and implemented.

The control software is subdivided into control functions allocated by the designer to the different processors.

Each control function has to be scheduled in term of period, duration and phase.

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Outstanding characterists: **Support to system design The two model approach**

In EICASLAB you can implement your control algorithms by following your own control design methodology.

In particular, you can follow a Model-Based approach and you can distinguish between:

- the model used for designing your control here called Simplified Model, and,
- the model used to simulate the plant to be controlled here called Fine Model.

The Simplified Model is typically linear and time invariant.

The Fine Model is typically non-linear and time variant and includes all the aspects neglected in the simplified model, but that may affect your control (like hysteresis, backslash...).

This approach – called the **two model approach** - allows you to test and tune your control algorithm, by assessing the limits of validity of the simplified model.

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Outstanding characteristics Powerful algorithms and oriented libraries

Each Working Area is equipped with libraries oriented to specific application sectors, easily customizable by the user.

To integrate the system of differential equations used to represent the Plant to be controlled, a fully original proprietary integration

 $\dot{x}=f(x, u, t)$ y=g(x, u, t)

procedure is available

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specifically developed for overcoming the frequent difficulties met as a consequence of the numerical errors.

To perform *Model Parameter* Identification, an original identification method is available in EICASLAB, oriented to estimate the best values of the plant simplified model parameters from the point of view of the control design.

To perform *Control Parameter* Optimisation, a powerful numerical optimisation algorithm is available, which allows in very reasonable computing time to get the optimum value of a large number of parameters.

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Outstanding characterists: Support to simulation

A "like real-time" technique is applied in simulation, capable to faithfully emulate the execution of the control architecture running on the final target.

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All the activities assigned to the Plant, Mission and Control Areas, together with data transmissions among blocks, are executed by strictly following the scheduling constraints set out by the user, in order to reproduce the order in which these activities will be really executed in the final target.

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Outstanding characterists:

Automatic code generation of the Application Software

Starting from the *Modelling and Like Real-time simulation* operative mode, the **Application Software** (AS) - that represents the "*target independent*" part of the final code to be transferred in the final target - can be automatically generated thanks to the EICASLAB ACG module.

We point out that the AS, generated and preliminary tested in "like real-time" in the *Modelling and Like Realtime simulation* operative mode, will be transferred and used **without modifications** in the other two operatives

> mode, will be transferred and used without modifications in the other two operatives modes, and especially it will be exactly the same one that will be transferred in the final target.

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EICASLAB tools to support the operative mode

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The Professional Software Suite for Automatic Control Design and Forecasting

To be continued!

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